Stanley Johnson

* Worked on having drone approaching a single obstacle and responding accordingly
* Established proper threshold pixel count for landing

Jeremiah Lockhart

* Worked on having drone maneuver around an obstacle correctly
* Worked on optimizing image recognition subsystem

Suzanne Thomas

* Worked on single obstacle avoidance
* Worked on repositioning of the drone after avoidance
* Worked on reassessing for open space after obstacle was avoided